**Work distribution**

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| --- | --- | --- | --- |
| Software portion | User Interface & Bluetooth data sending | **Rhythm** | Complete |
| Retrieving photo from Bluetooth connected camera | **Rhythm** | Complete |
| Robot hardware | Wheel-motor rotation & speed calculations | **Limon + Sourov** | Complete |
| Arm-motor rotation | **Limon + Sourov** | Complete |
| Bluetooth signal receiving | **Rhythm** | Complete |
| Infrared sensor & robot positioning | **Nayem + Mazhar** | Cancelled |
| Sonar(Ultrasonic) sensor | **Nayem + Mazhar** | Cancelled |
| Mechanical structure | Car structure | **Rhythm** | Complete |
| Robotic arm structure | **Rhythm** | Complete |
| Microcontroller programming | Coding, Testing, Debugging & Further improvement | **All** | Complete |